



# The NCAR/NOAA Global Hawk Dropsonde System

## Progress and Lessons Learned

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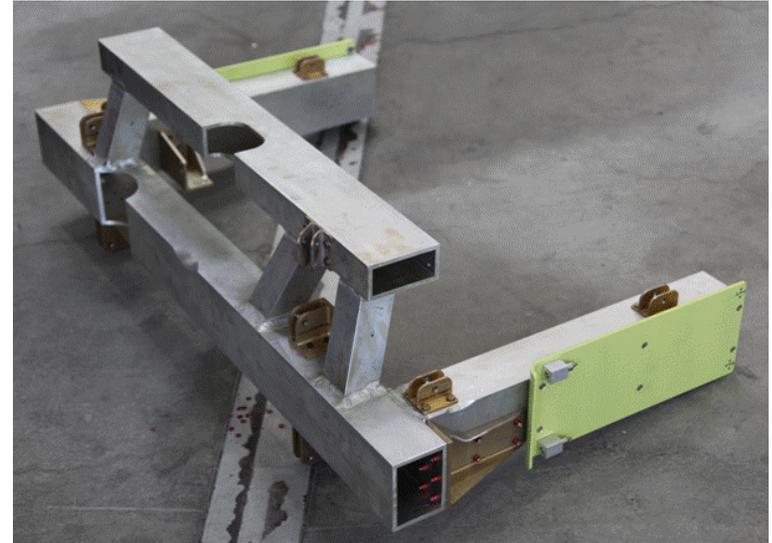


# Global Hawk Dropsonde Overview

- Developed through collaborative partnership between NOAA, NCAR, and NASA
- Relies on NCAR/EOL's long experience with dropsonde development and launching
- Uses AVAPS-3 system and new Global Hawk sonde: smaller and lighter than current dropsondes
- System has 89-sonde and 8-channel capacity
  - 6 channels currently active
  - 72 sonde capacity during WISPAR; 89 by HS3
- D-file returned to ground following drop
- Ground processing enables GTS transmission

# What Happened During GRIP?

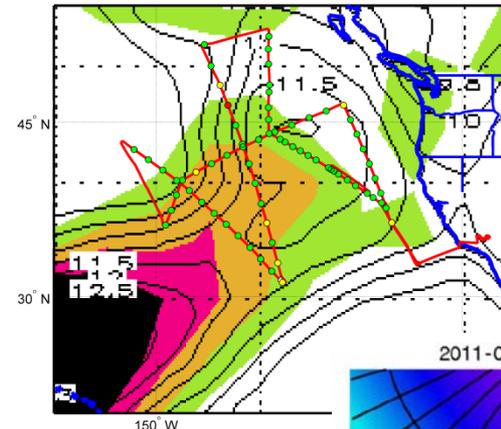
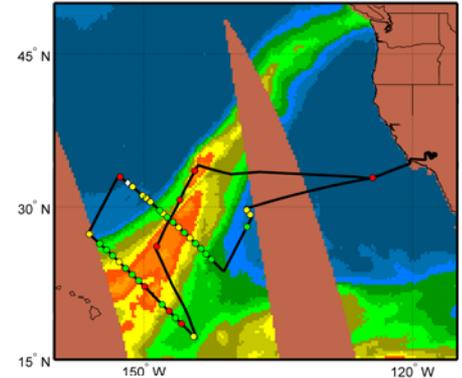
- Initial installation delayed due to delays in system completion and fabrication of mounting frame
- Installation and ground testing completed successfully
- Successful launch of first sonde at 15,000 ft on 24 Aug
- Sonde jammed in launcher on second launch attempt
  - Problem traced to safety latch
- NCAR unable to field reworked latch based on solenoid design by end of GRIP
  - Modified and alternate designs explored in Boulder
  - Solenoid design pursued for GRIP due to impacts on system electronics
  - Static performance good but could not pass vibration testing



# Progress Since GRIP

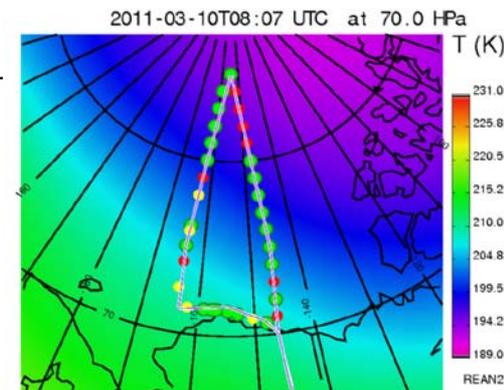
- System functional!
- NCAR redesigned the safety latch using a cylinder brake
- System passed all required testing and performed very well during WISPAR Experiment
  - 177 sondes deployed over 3 flights
- IR Communication issues resolved during WISPAR campaign
- Demonstrated capability of having all 6 channels active simultaneously
- Good engineering test including extreme Arctic conditions
- Capacity and minor improvements in progress now

Atm. Rivers  
11–12 Feb  
37 sondes



Winter  
Storms  
3–4 March  
70 sondes

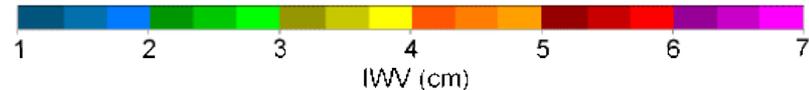
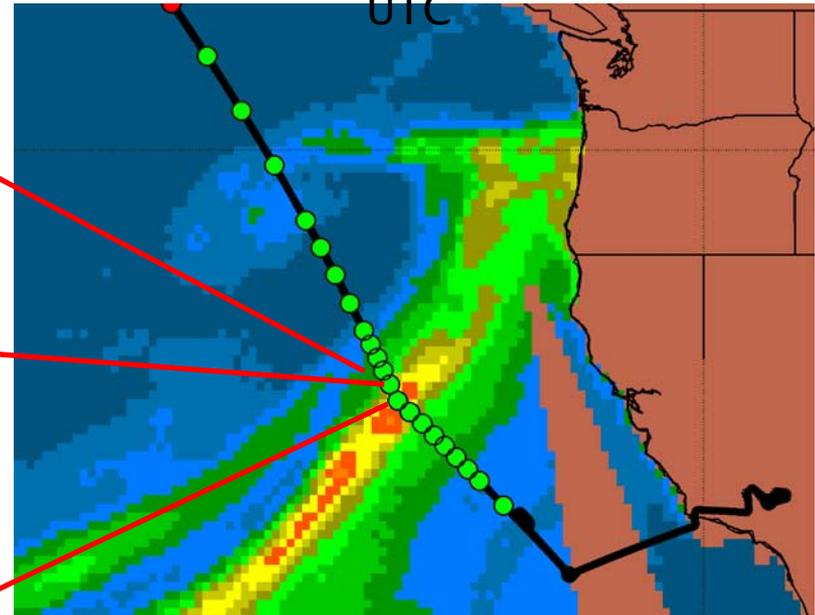
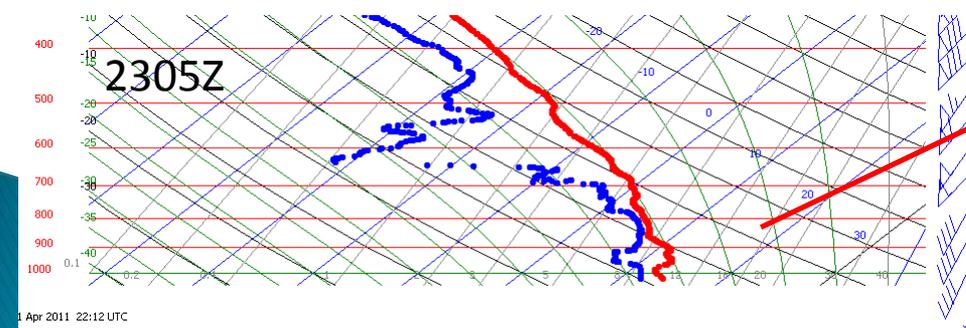
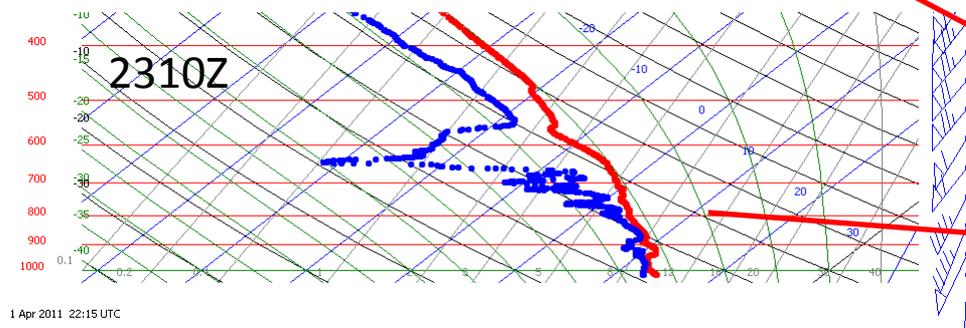
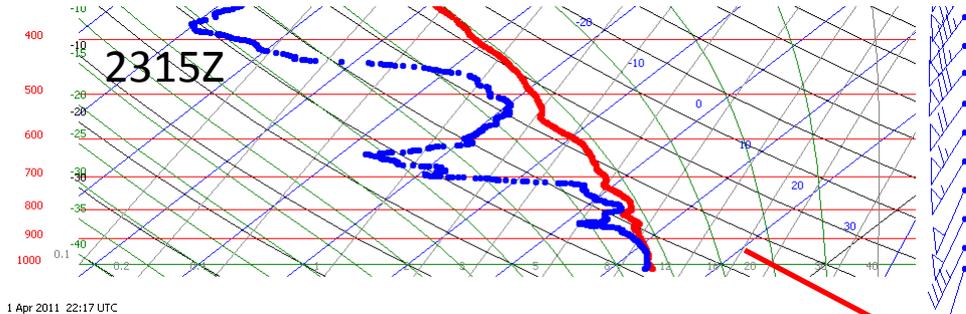
Arctic Weather  
9–10 March  
70 sondes  
35 N of AK



# Sample Results

## Northbound AR Crossing Arctic Flight, 10-11 March

SSMIS F17 10 Mar 2011, ~0200 UTC



# Lessons Learned

- Dropsonde system functional and ready for HS3
- Flexibility exists in dropsonde deployment
  - Location not need to be specified before flight
  - Able to specify lines and regions for dropsonde deployment and alter in flight
  - Working with New York Oceanic may be more challenging – but successful experience with Oakland invaluable
- Workload high for pilots, payload manager, and operators
  - Pilots in communication with ATC prior to each drop
  - Drop location transmitted over radio
  - Multiple radio calls between front and back room
  - Likely not possible for one operator to launch, monitor, and do ASPEN processing
  - Should explore data processing at external location



# HS3: A Multi-Year Investigation of Hurricane Formation and Intensity Change

The HS3 logo features a blue and white spiral with two blue aircraft silhouettes flying in a circular path. The text "NASA HURRICANE AND SEVERE STORM SENTINEL HS3" is overlaid on the spiral.

**NASA**  
**HURRICANE**  
**AND SEVERE**  
**STORM**  
**SENTINEL**  
**HS3**

**PI: Scott Braun**

**Deputy PI: Paul Newman**

**PM: Marilyn Vasques**

**PS: Ramesh Kakar**



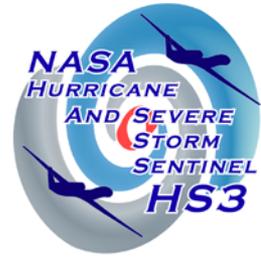
# Overall Science Objective



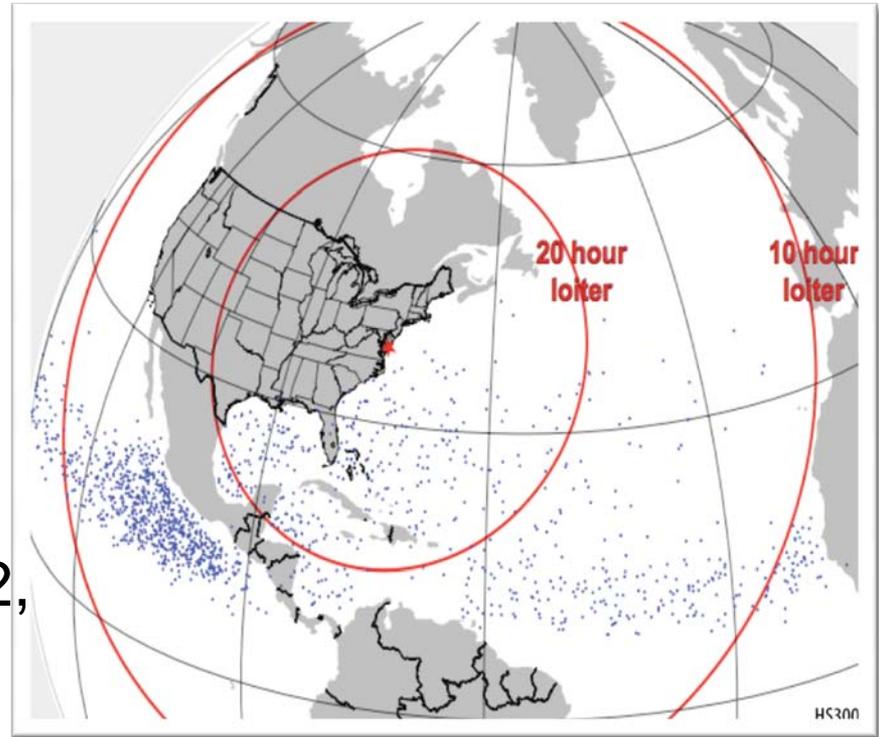
- To provide measurements to address key science questions related to storm formation and intensity change, including whether it is primarily a function of the storm environment or storm internal processes. Emphasis on:
  - The structure and role of the SAL, dust transport
  - Genesis processes
  - Convective bursts and wind field changes
  - Warm-core formation and evolution



# HS3 Mission Overview



- Two aircraft, one equipped for the storm environment, one for over-storm flights
- The GHs will not do simultaneous science operations
- Deployments of GHs from the East Coast, likely Wallops Flight Facility in VA
- One-month deployments in 2012, 2013, and 2014, 300 flight hours per deployment

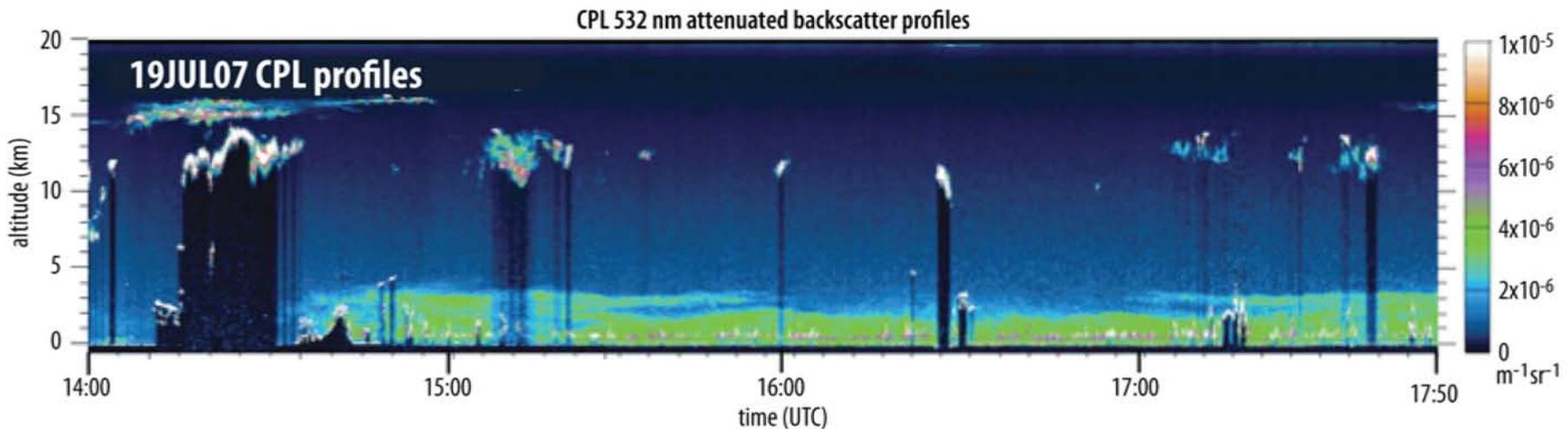


Dots indicate genesis locations. Range rings assume 30-h flights.

# Instruments: Cloud Physics Lidar



- ▶ Cloud/aerosol lidar (CALIPSO simulator)
- ▶ Instrument PI: Matt McGill, NASA/GSFC
- ▶ Data: Profiles of atten. backscatter, cloud/aerosol boundaries, optical depth, extinction, depolarization
- ▶ Horiz., vertical resolution=200 m, 30 m



# Instruments: Dropsondes (AVAPS)



- ▶ Instrument PI: Gary Wick, NOAA
- ▶ Data: High-resolution vertical profiles of temperature, humidity, pressure, winds
- ▶ Potentially up to 70–90 drops per flight
- ▶ New design has flown on GH
  - ▶ Test flights (low, mid, high alt.) completed 2/4/11
  - ▶ NOAA science flights ongoing





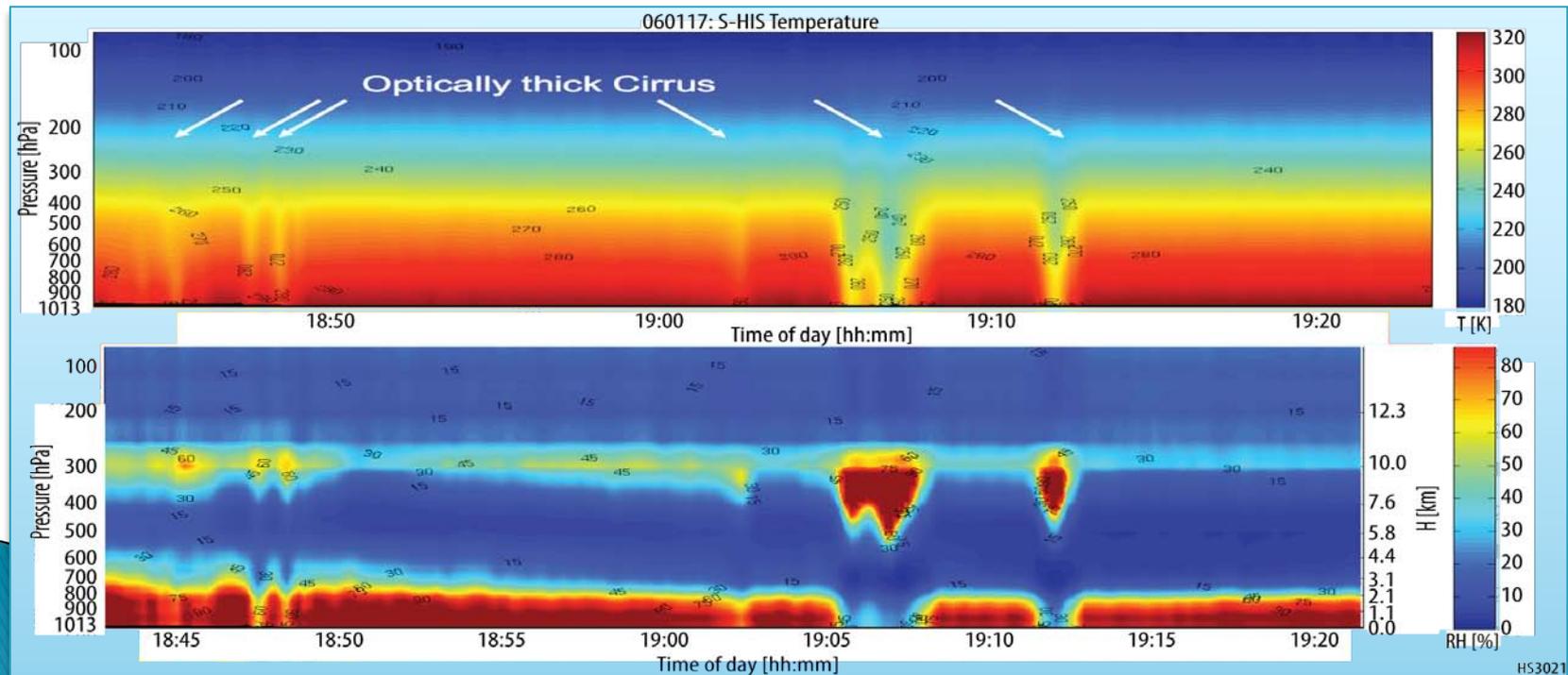
# HS3 Specifics

- Planning for 500 sondes for each year of the experiment (2012, 2013, 2014)
- Transmission of data on GTS a NOAA priority
  - Exploring testing of coincident drops with standard sondes
  - Model impact study using data from WISPAR Winter Storms flight
- Operation likely to transition from NCAR to NOAA during the experiment

# Instruments: Scanning High-resolution Interferometer Sounder

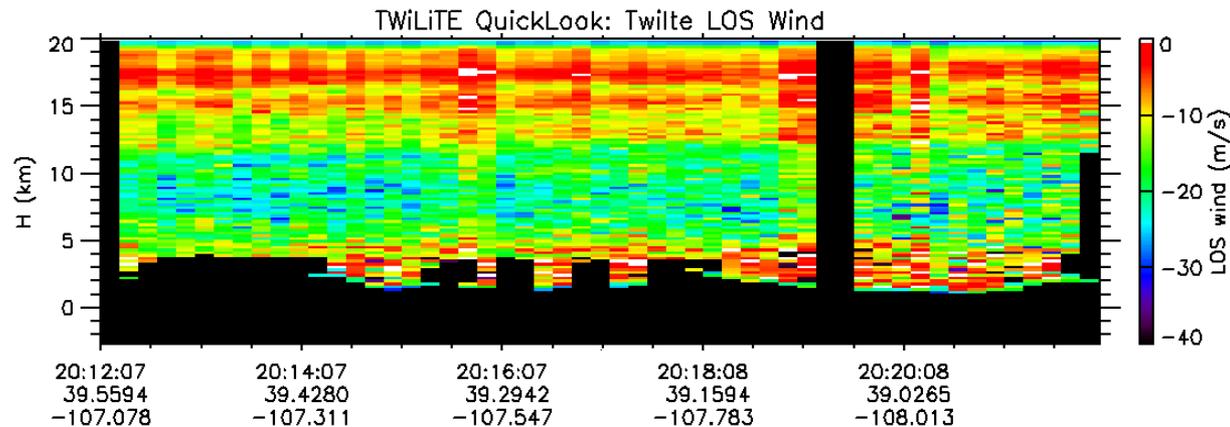
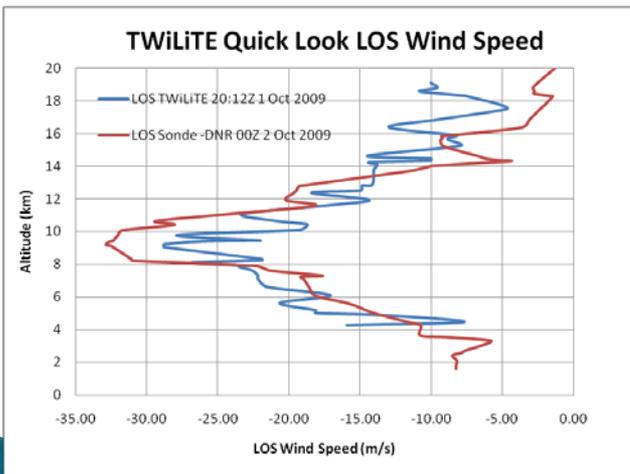


- ▶ Instrument PI: Hank Revercomb, Univ. Wisconsin
- ▶ Data: IR TB spectra; Cloud-top temperature, height; sfc skin temperature; **profiles of temperature and water vapor in clear-sky conditions**
- ▶ Horiz., vertical resolution=2 km, 1–3 km



# Instruments: TWiLiTE Wind Lidar

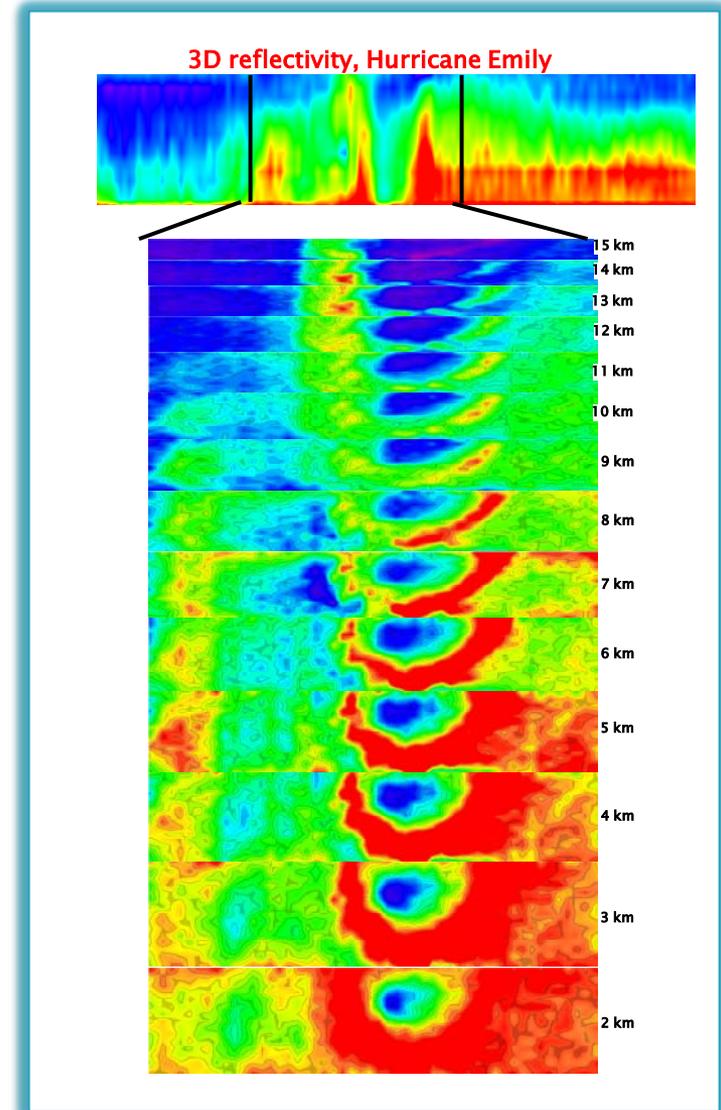
- ▶ Instrument PI: Bruce Gentry, NASA/GSFC
- ▶ Data: Profiles of backscatter intensity, Doppler velocity, horizontal winds in clear-sky conditions
- ▶ Will fly as part of HS3 in 2013–14 only due to NGC schedule, wind pod availability
- ▶ Horiz., vertical resolution= $\sim 2$  km radial winds, 8 km for retrieved horizontal winds, 250 m



# Instruments: High-Altitude MMIC Sounding Radiometer (HAMSR)



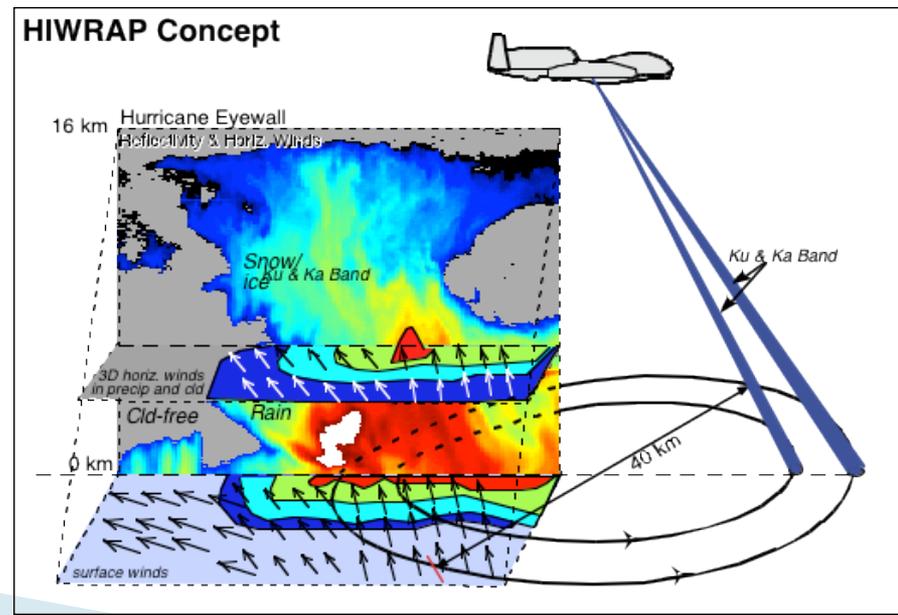
- ▶ Instrument PI: Bjorn Lambrigtsen, JPL
- ▶ Data: Calibrated brightness temperature; vertical profiles of temperature and water vapor and liquid water; precipitation structure
- ▶ Horiz., vertical resolution=2km, 1-3 km



# Instruments: High-altitude Imaging Wind and Rain Airborne Profiler (HIWRAP)



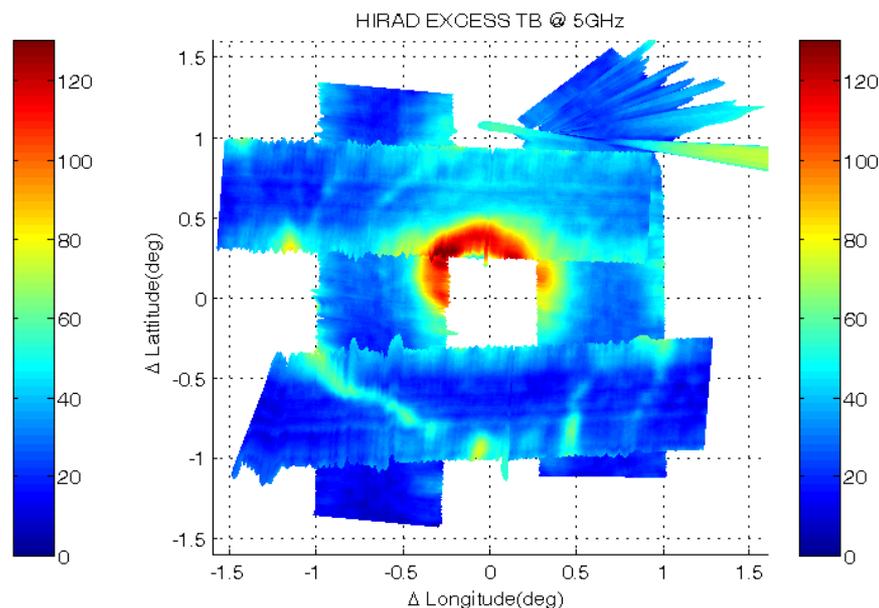
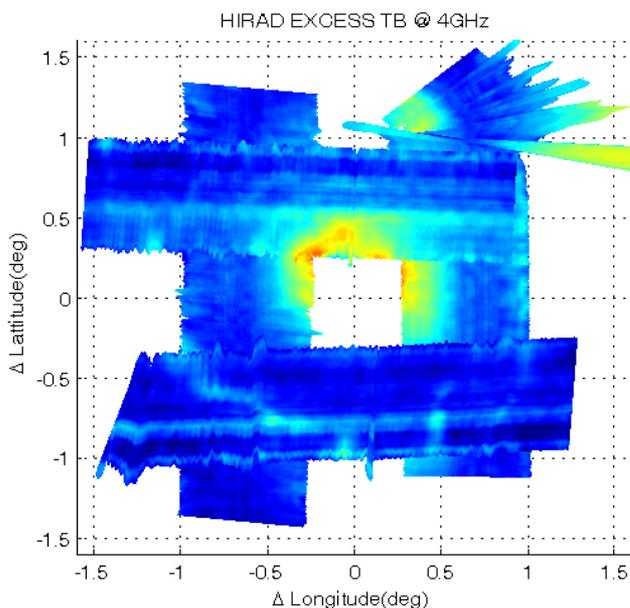
- ▶ Instrument PI: Gerald Heymsfield, NASA/GSFC
- ▶ Data: Calibrated reflectivity, Doppler velocity, 3D reflectivity and horizontal winds, ocean surface winds in precipitation free areas
- ▶ Horiz., vertical resolution=
  - ▶ 1 km, 200 m for dBZ, Doppler velocity
  - ▶ 1 km, 500 m for horiz. winds
  - ▶ 2 km for surface winds



# Instruments: Hurricane Imaging Radiometer (HIRAD)



- ▶ Instrument PI: Tim Miller, NASA/MSFC
- ▶ Data: Surface wind speed, rain rate, and temperature; brightness temperature fields at 4 frequencies
- ▶ Technology similar to NOAA's SFMR, but scans cross track instead of just nadir
- ▶ Horiz. resolution= $\sim 1.5$ – $2.5$  km



Example  
from  
Hurricane  
Earl flight  
during GRIP

# Extra Slides



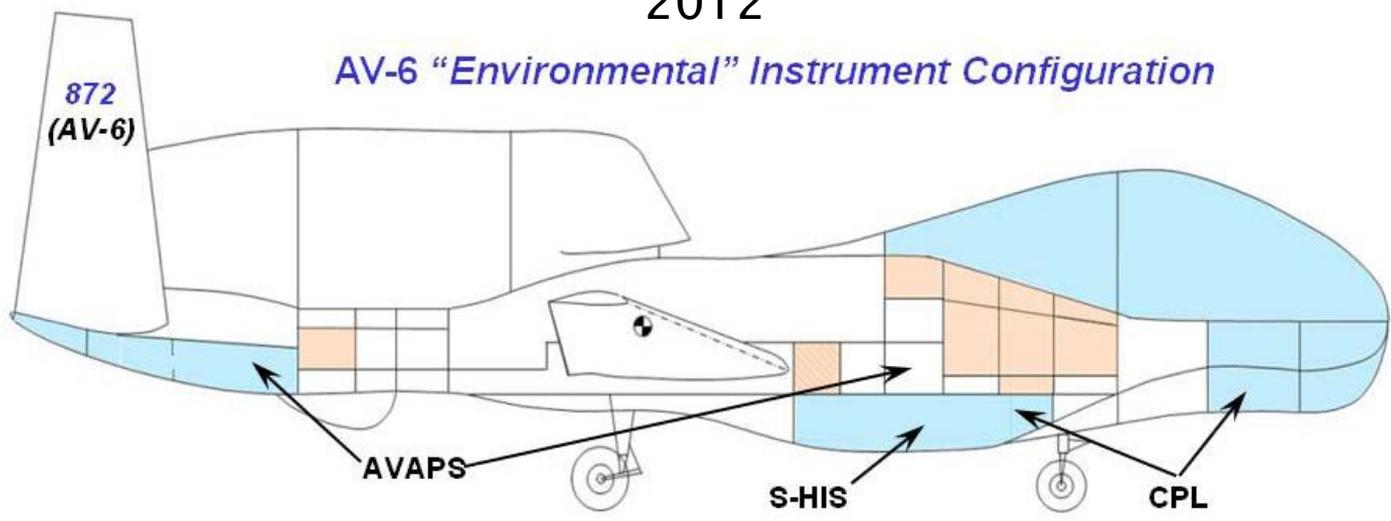
- ▶ Extra Slides



# Environmental Payload

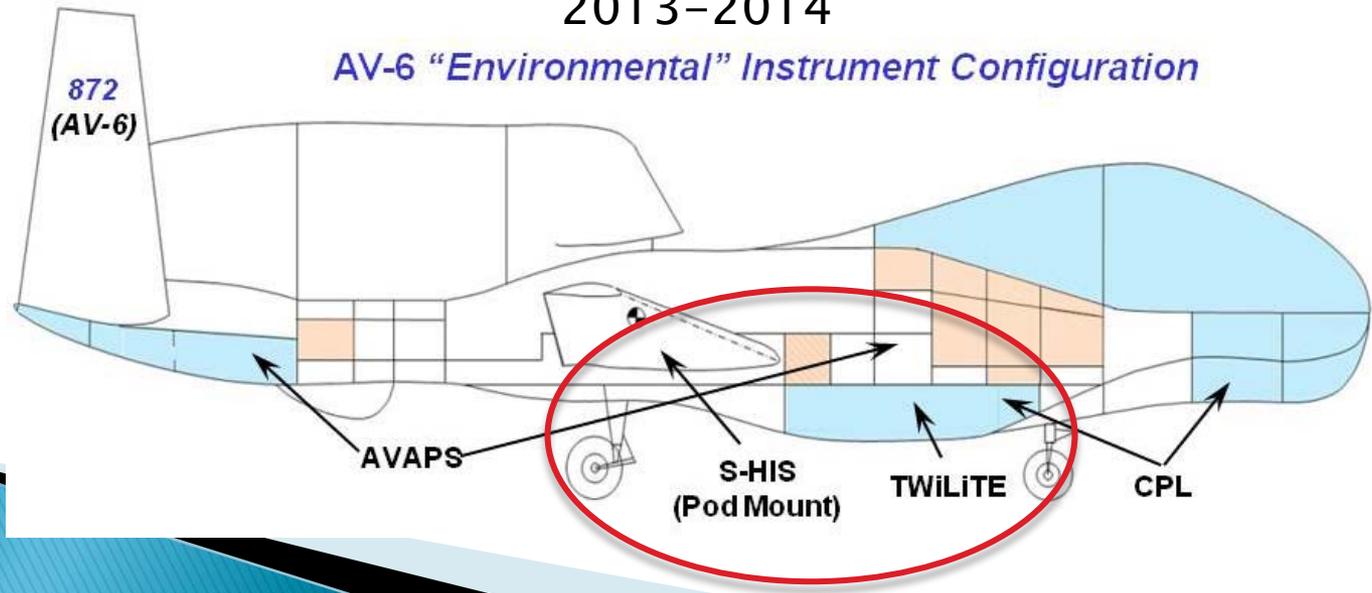
2012

AV-6 "Environmental" Instrument Configuration



2013-2014

AV-6 "Environmental" Instrument Configuration

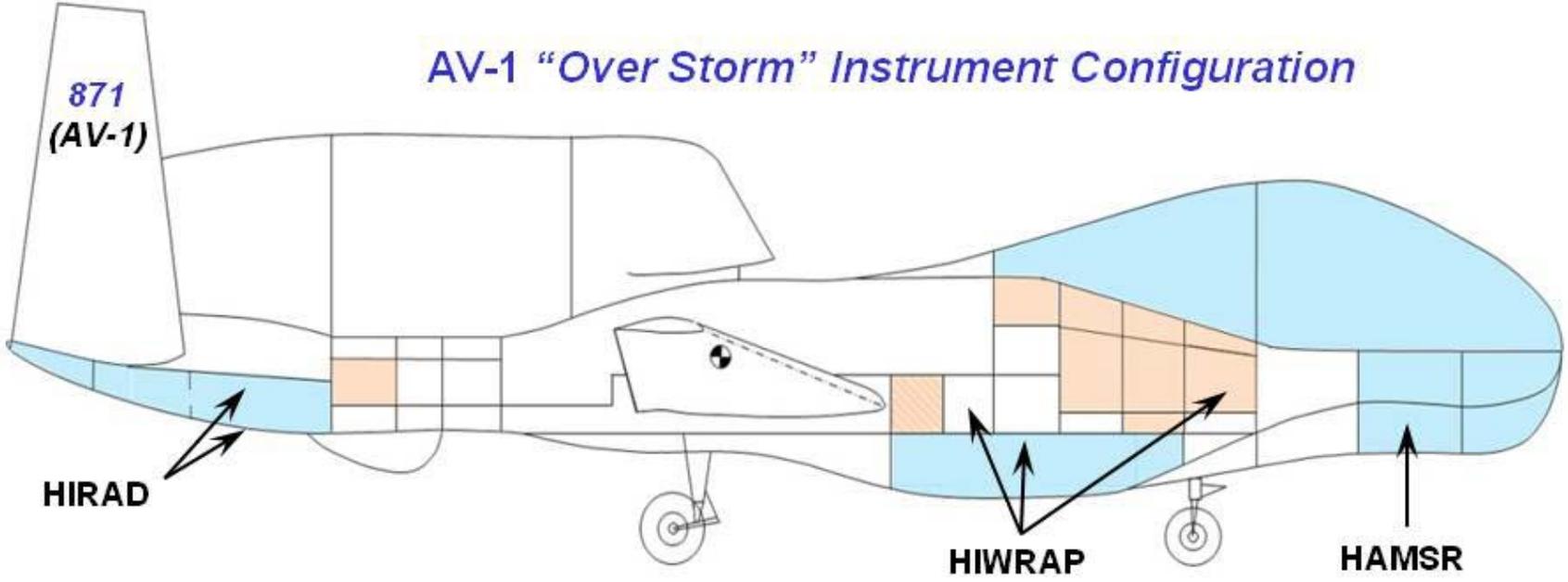




# Over-Storm Payload



AV-1 "Over Storm" Instrument Configuration





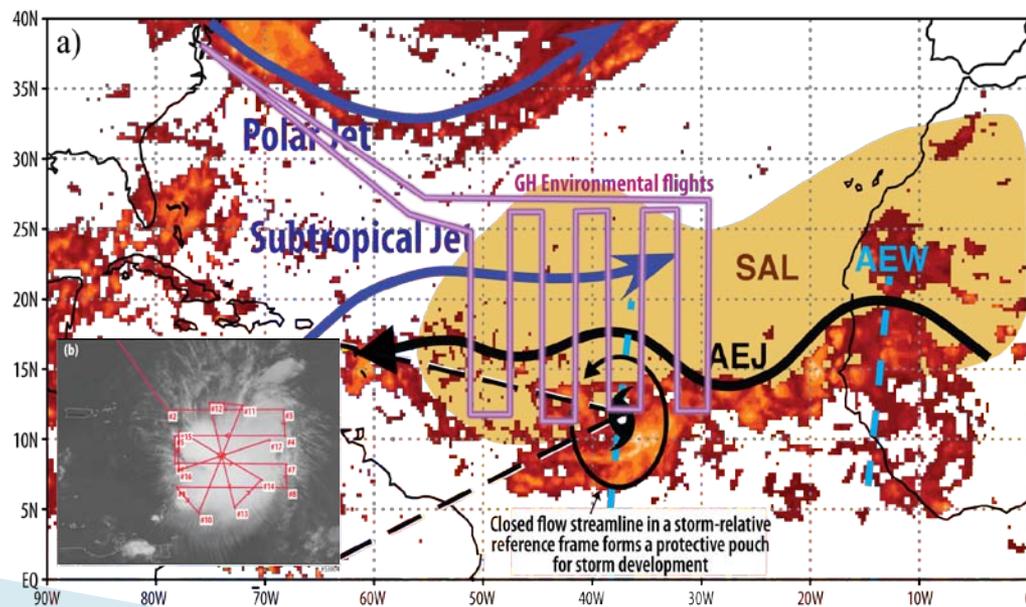
# Sampling of the Environment



- Environmental observing suite unique for examining the SAL
  - Coincident dust, thermodynamics, and wind measurements
  - Sampling in central and eastern Atlantic, where SAL characteristics can be much different than to the west
- Able to reach early genesis regions of the eastern Atlantic not usually accessible

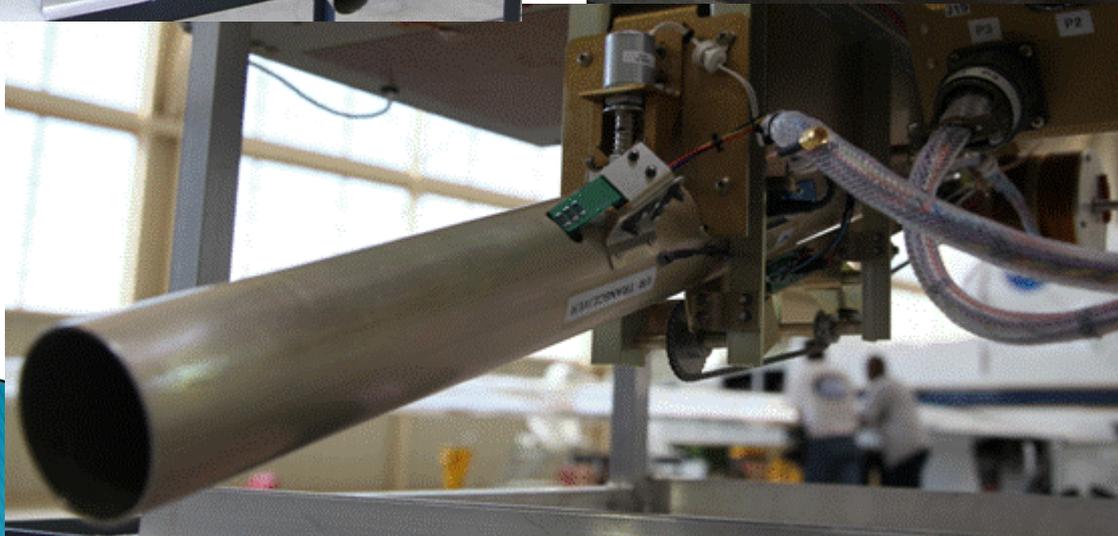
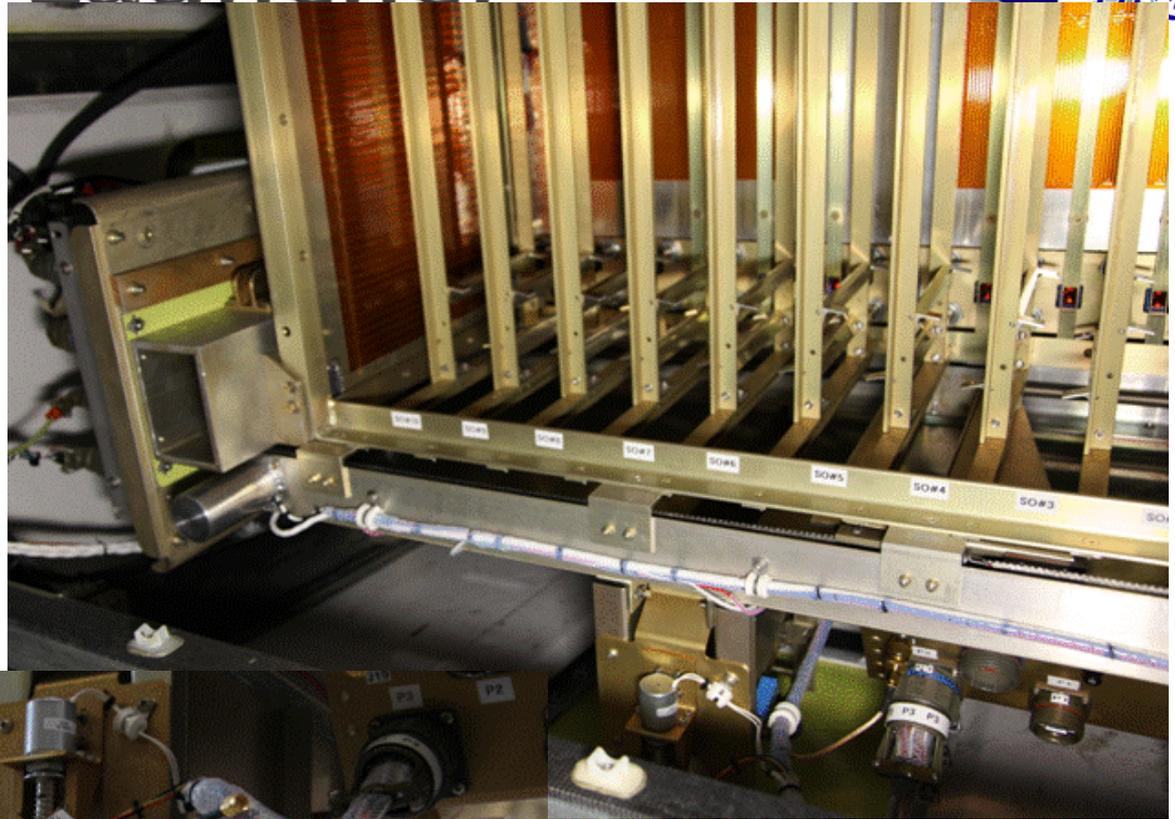
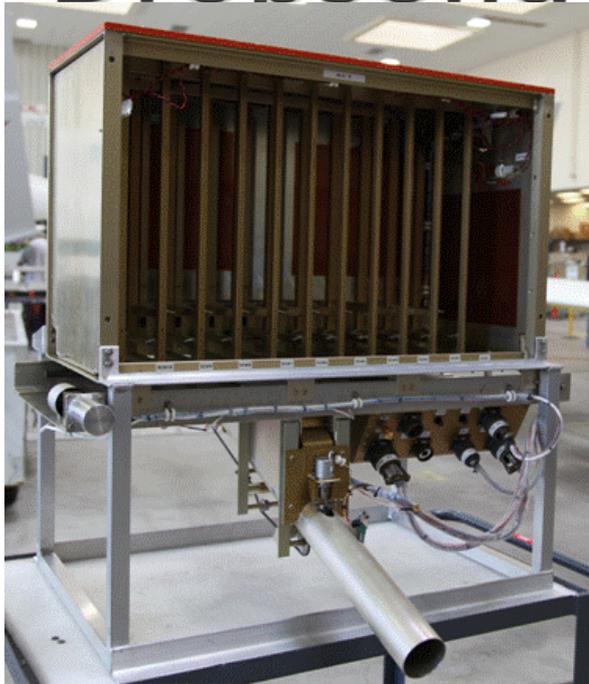
Enhancements to models:

- Validation of global analyses of SAL structure and evolution
- Evaluation of dust transport
- Improved initial conditions for simulations and forecasts

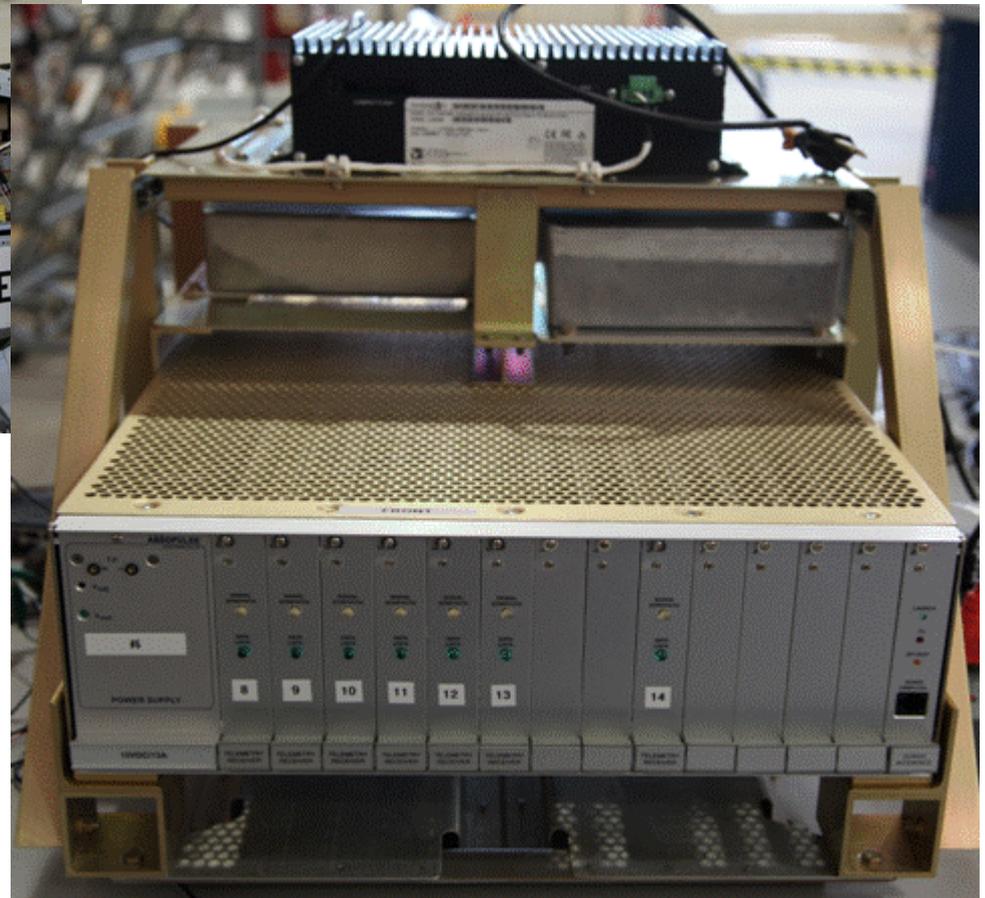




# Dropsonde Launcher



# AVAPS Electronics



# Initial Sonde Specifications

- Size: 4.56 cm dia. X 30.5 cm length
- Mass: ~175 g
- Fall rate: ~12 m/s at surface
- Sensors based on Vaisala RS-92 radiosonde sensor module
  - Temperature: +60° to -90 ° C , 0.1 ° C resolution
  - Humidity: 0 to 100 %, 1 % resolution
  - Pressure: 1080 to 3 mb, 0.1 mb resolution
  - 2 Hz update rate
- Winds based on OEM GPS receiver and position
  - 4 Hz update rate
- Stable cone parachute design
- Remote control of power on/off and sonde release
- Designed for extreme environmental conditions

